

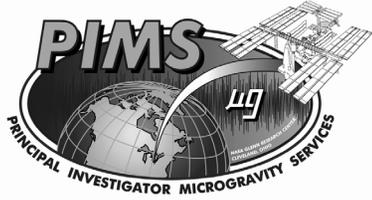
Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Section 10

Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

Richard DeLombard
Acceleration Measurement Discipline Scientist
NASA Glenn Research Center

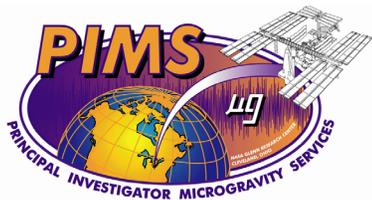


Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Acceleration measurements for experiments

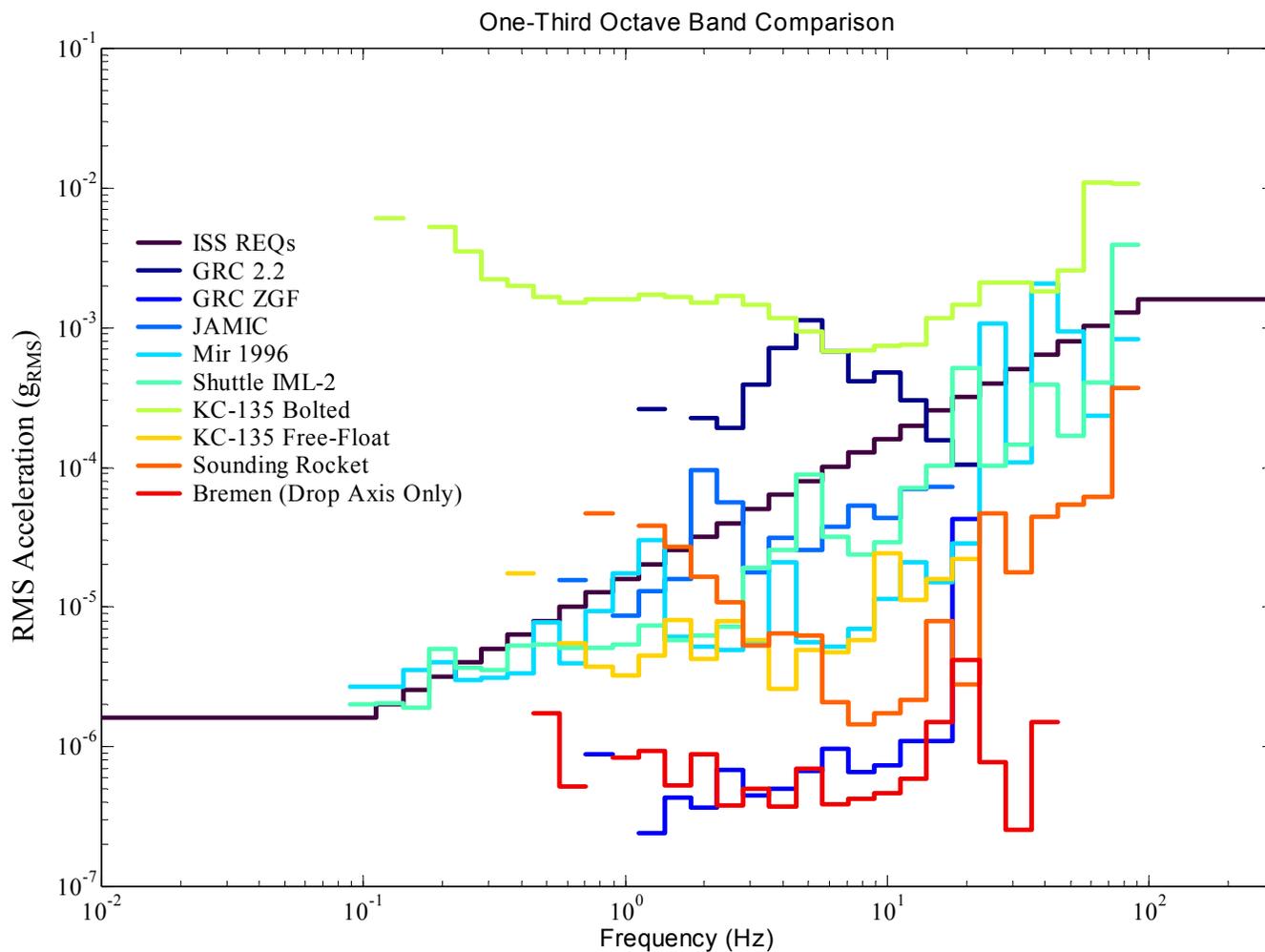
- **Experiments in microgravity are disturbed by accelerations (e.g. vibrations, shocks, gravity gradient, linear motion)**
- **Experiments in ground laboratories are disturbed by accelerations also**
 - **Gravity (very pervasive!)**
 - **Elevator motions in laboratory building**
 - **Traffic nearby building (e.g. street, loading dock)**
 - **Air conditioning equipment (e.g. compressor, fans, etc.)**
 - **Clumsy lab assistants**
- **Accelerations should be measured during experiment ground operations - not just during orbital operations**



Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Residual acceleration for various microgravity facilities

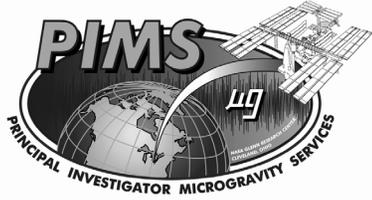


(from Ross, 2001)



Methods of creating 'zero-g' or microgravity

- **Center of Earth's mass ($g_e \sim 0 \text{ m/s}^2$)**
 - Impractical location for experiment operations
- **Very distant from Earth or other celestial body ($g_e = 10^{-6} \text{ m/s}^2$)**
 - Impractical location for experiment operations
- **Free fall**
 - Zero horizontal velocity -----> drop tower ($g_e = 9.8 \text{ m/s}^2$)
 - 400 kph horizontal velocity -----> aircraft ($g_e = 9.8 \text{ m/s}^2$)
 - 30,000 kph horizontal velocity -----> orbital ($g_e \sim 9 \text{ m/s}^2$)
 - Where g_e is the acceleration due to Earth's gravitational pull
- **The reduced gravity features comes from free fall, not the absolute reduction or elimination of Earth's gravitational acceleration!**



Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Ground-based facilities with zero horizontal velocity

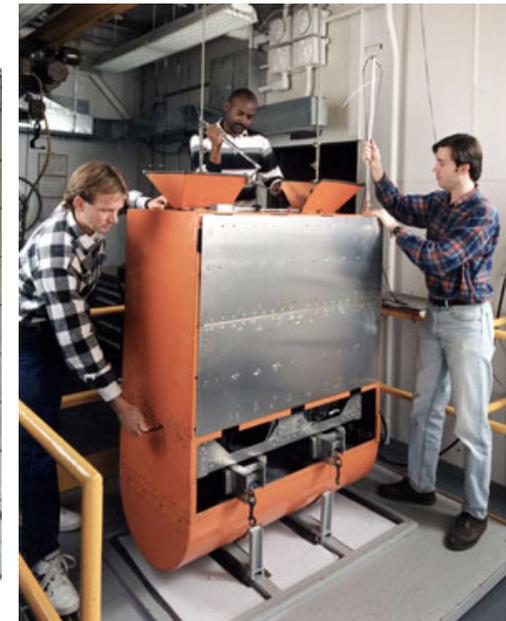
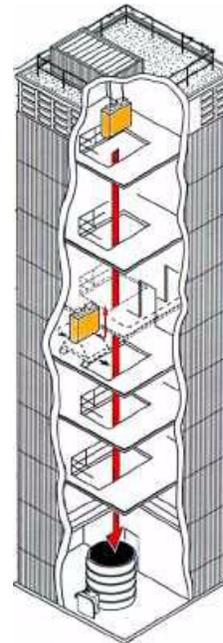
- **Seismic mass / vibration isolation**
 - **Not free-fall but vibrationally quiet**
 - Still 1-g environment
 - **Isolated floor mass**
 - **Vibration isolation platform**
- **Drop tower**
 - **Carrier containing experiment is dropped**
 - **Experiments may be complex**
- **Drop tube**
 - **Sample material only is dropped**
 - **Most often sample is molten metal drops**

Ground Facilities with zero horizontal velocity



NASA
C-99-2309
National Aeronautics and Space Administration
John H. Glenn Research Center at Lewis Field

**Seismic Mass
Plum Brook Station**
Base of huge vacuum chamber
(illustrative of method to utilize
vibration-quiet laboratory conditions)



**2.2 Second Drop Tower
NASA Glenn**
Drag shield being assembled for an
experiment drop



Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

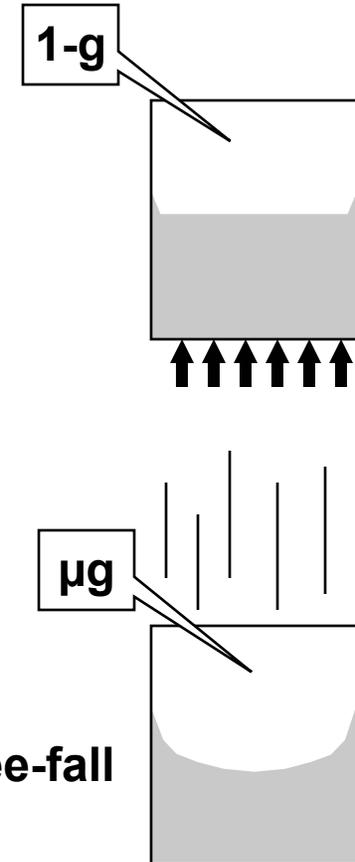


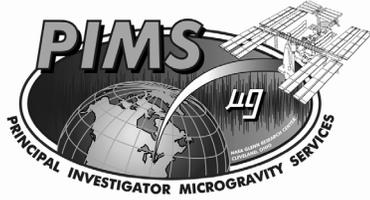
SPF Seismic Mass Characterization

- **Figure 10-1 illustrates the conditions existing on a large mass of concrete**
 - **Concrete foundation of world's largest vacuum chamber**
 - **The X-axis was vertical**
 - **$a = F/m$ implies low levels of acceleration with large value of mass with nominal forces from ground and wind**

Free-fall vs. 1-g

- **1-g condition**
 - Gravity effects are apparent when a retarding force disturbs free fall
 - Beaker exerts a force to stop water from falling
 - Floor exerts a force on people (felt as their weight)
- **Microgravity condition in a free fall**
 - Gravity effects are not apparent in free fall
 - **Beaker falls with the fluid**
 - beaker is no longer exerting a retarding force on water
 - sedimentation and buoyancy are reduced
 - surface tension & capillary forces are 'revealed'
 - **Acapulco cliff divers feel weightless during their free-fall to the ocean**





Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

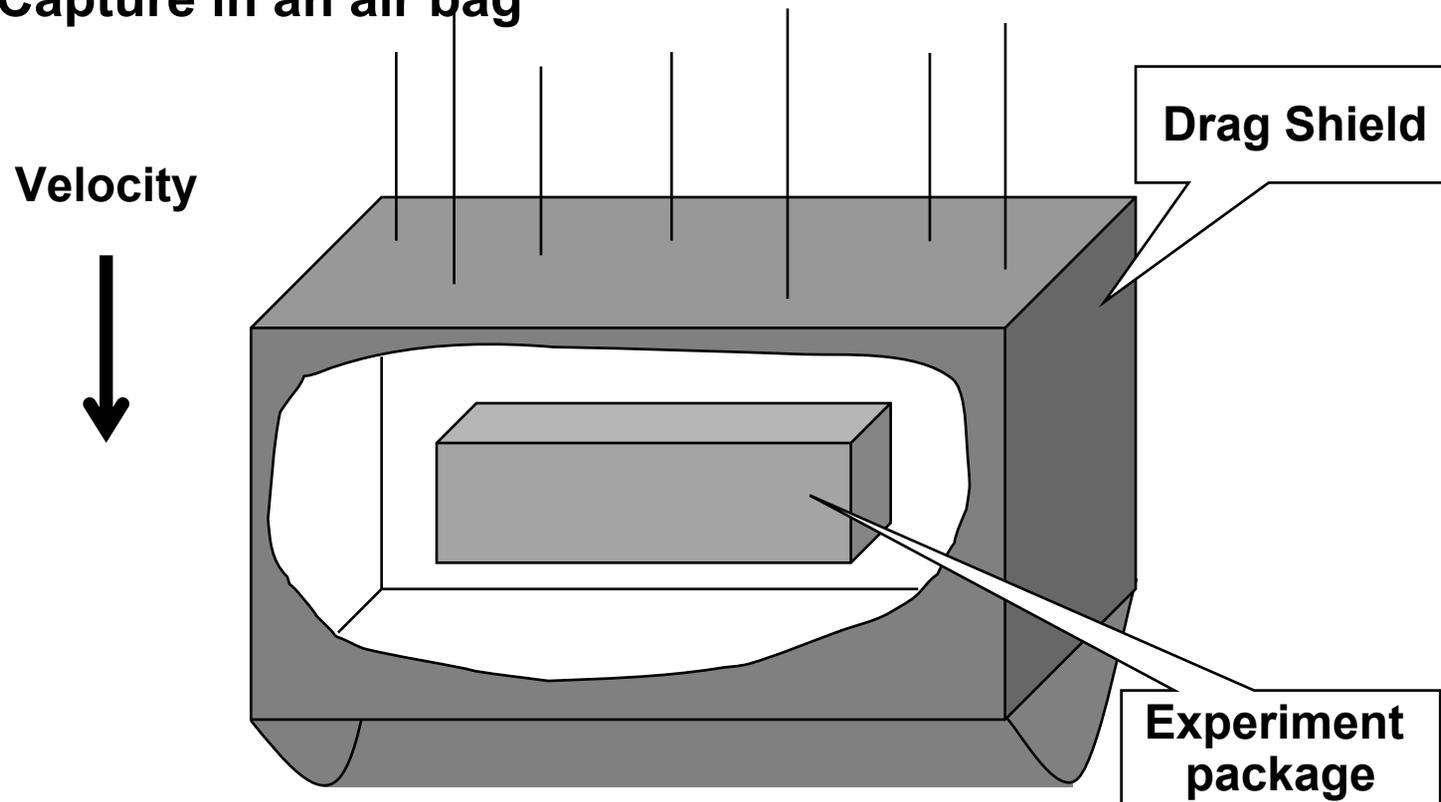


Drop Towers & Tubes

- **Drop towers attempt to minimize external forces**
 - **Air drag is a large external force**
 - Steady force which gradually increases with increasing velocity
 - **Several mechanisms are used to counteract air drag**
 - Drag shield
 - Experiment package surrounded by free falling container
 - Vacuum operation
 - Evacuate air from the chamber in which the experiment is dropped
 - Drag force compensation
 - Apply compensating force (thrust) to experiment carrier
 - **Keys for a 'quiet' drop**
 - Smooth release mechanism to minimize initial transient vibration
 - Structural relaxation depends on design of carrier and experiment
 - Dynamically balance moving experiment and carrier components

Drag Shield

- NASA GRC 2.2 Second Drop Tower uses a drag shield
- Capture in an air bag

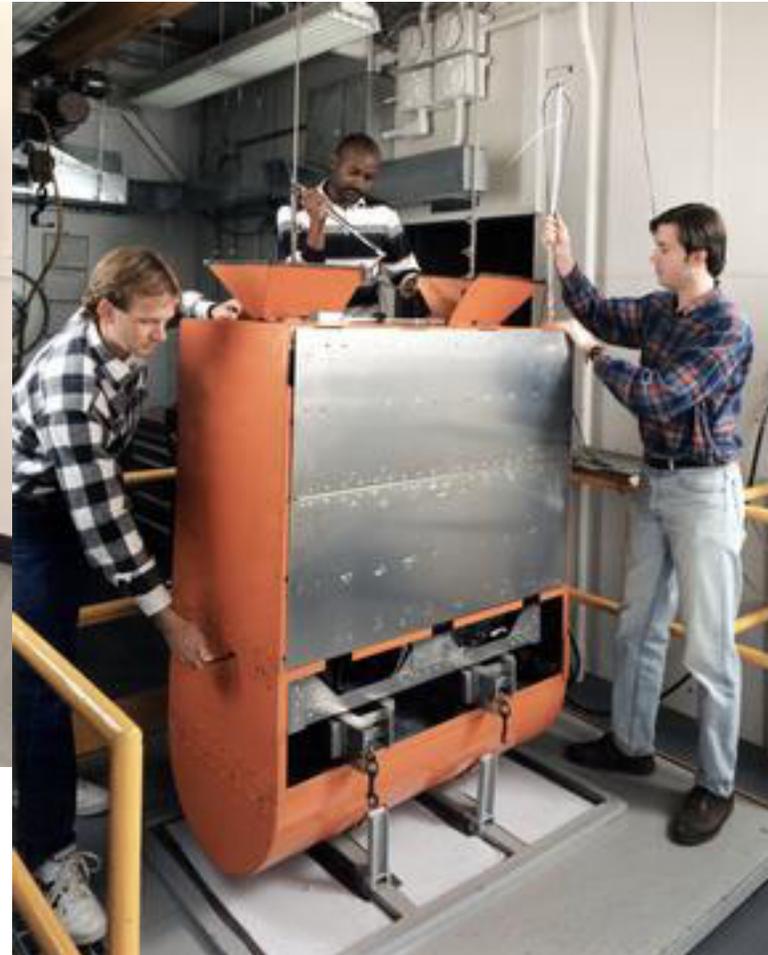


NASA GRC 2.2 Second Drop Tower



Experiment rig assembly ▲

Drag shield preparation ▶

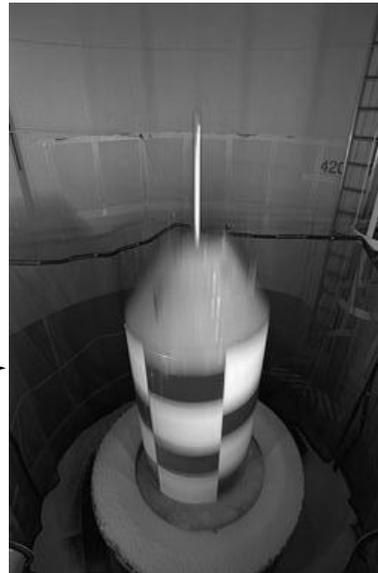


March 2003

Vacuum Operation

- **Vacuum drop towers include:**
 - **Zero Gravity Research Facility at NASA GRC**
 - Capture in foam pellet container
 - **ZARM facility at University of Bremen, Germany**
 - Capture in foam pellet container

Experiment capture in Zero Gravity Research Facility



March 2003

ZARM tower exterior

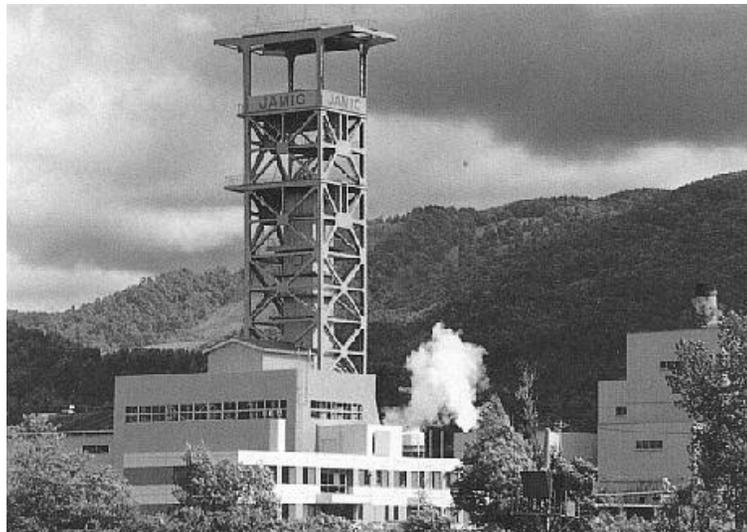


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Drag Force Compensation

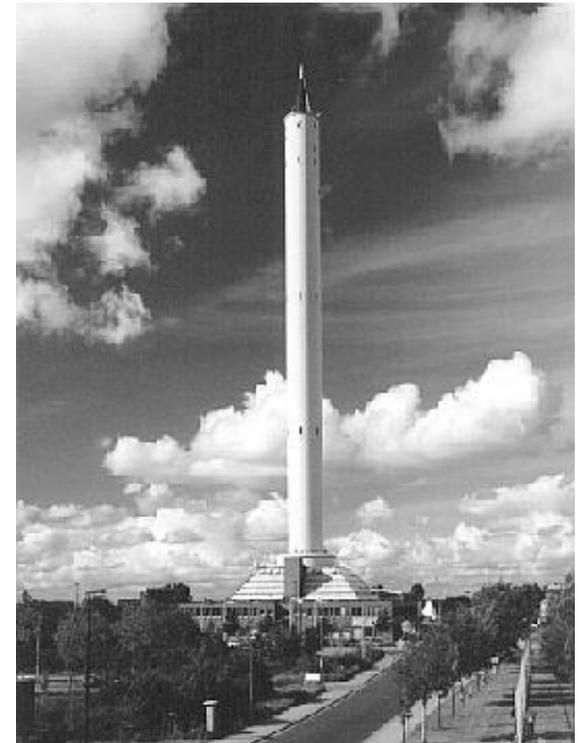
- **Japan Microgravity Center**
 - **Inner & outer capsule (i.e. drag shield)**
 - Vacuum drawn between inner & outer capsules
 - **Acceleration added to outer capsule for drag compensation**
 - Cold-gas jet
 - **Capture accomplished with air pressure then mechanical brake**

JAMIC

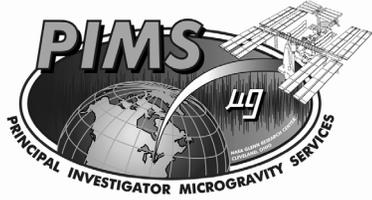


Drop Tower Comparison

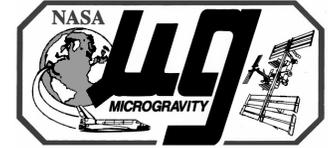
- **NASA GRC 2.2 Second Drop Tower**
 - 2.2 seconds 24.1 m 10^{-4} g
- **ZARM Drop Tower**
 - 4.74 seconds 123 m 10^{-5} g
- **NASA GRC Zero Gravity Research Facility**
 - 5.18 seconds 145 m 10^{-5} g
- **Japan Microgravity Center**
 - 10 seconds 490 m 10^{-5} g



ZARM

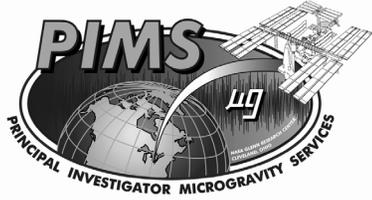


Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Acceleration Environment Features of Drop Towers

- **Release**
 - **Step change transition from 1-g to sub-milli-g level**
 - **Transition occurs over very short time that the mechanism actually releases carrier**
- **Vibrations from release mechanism**
 - **The release transition is similar to ringing a bell**
 - Step change causes (unwanted) vibration in experiment carrier
 - The 'bell ringing' is damped by carrier and experiment mechanical design
 - **May persist for major portion of microgravity time**
- **Figure 10-2**

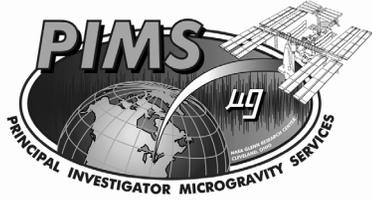


Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



Acceleration Environment Features of Drop Towers

- **Vibrations from experiment equipment operation, such as:**
 - **Camera shutters**
 - **Film transport**
 - **Solenoid and relay actions**
 - **Pumps**
 - **Motor-driven fluid mixers**
 - **Figure 10-3**
- **High level of deceleration at capture**
 - **Levels depend on capture mechanism and final velocity**
 - **Figures 10-2 and 10-4**



Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

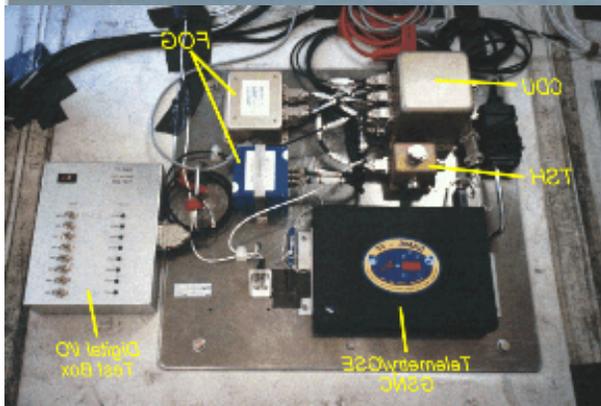


Non-orbital flight platforms (~ 200 mph horizontal velocity)

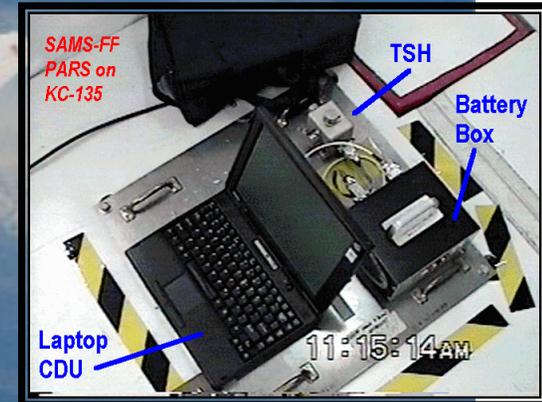
- **KC-135 aircraft (NASA)**
 - Operated by NASA Johnson Space Center
 - Each parabola provides 15-20 seconds of reduced gravity environment
 - Periodic free-fall interspersed with high-g pull-out
 - Approximately 40-50 parabolas per flight (campaign)
- **Terrier-Black Brant sounding rocket**
 - Achieves free-fall conditions on the order of 500 seconds after motor burn-out
 - One of several types of sounding rockets

Aircraft Facilities

KC-135

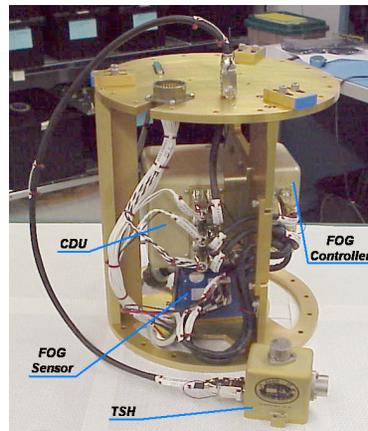


SAMS-FF / KC-135
Linear acceleration sensors
and fiber optic gyro sensor



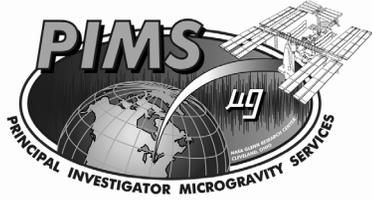
Parabolic Aircraft Rating System
Linear acceleration sensors
and software processing

Sounding Rockets



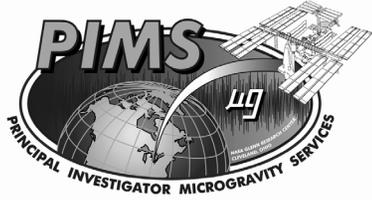
SAMS-FF / Sounding Rocket
Linear acceleration sensors and
fiber optic gyro sensor





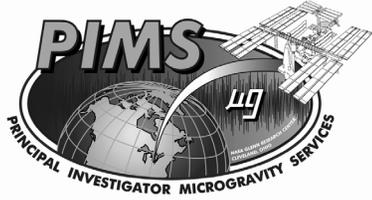
KC-135 Environment Characterization

- **Figure 10-5 illustrates the KC-135 overall environment over multiple parabolas during a typical campaign**
- **Figure 10-6 is a detailed plot of the KC-135 environment during the reduced gravity portion of the parabola**
- **Figure 10-7 is a plot of KC-135 parabola recorded in support of SAL experiment. Shows free-float of SAL test equipment and timelines the activity within the parabola**
- **Figure 10-8 is a detailed plot of the free-float period of the parabola**



Sounding Rocket Environment Characterization

- Terrier-Black sounding rocket DARTFire flight timeline is shown in the graphic in Figure 10-9
- Figure 10-10 illustrates the acceleration vector magnitude for the time period when the sampling rate was 25 samples per second
 - environment measured to be less than 30 micro-g root sum square (RSS) for the time interval analyzed
- Figure 10-11 is the RSS power spectral density for the time period when the sampling rate was 25 samples per second
 - frequency domain characteristics track known disturbance sources from the DARTFire equipment
 - Intensified Multispectral Imager filter wheel operates at 5 Hz
 - Infrared Imager filter wheel operates at 1 Hz

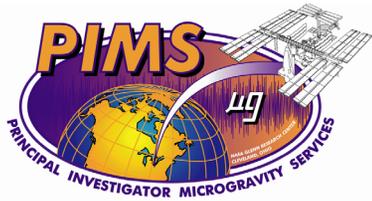


Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms



References

- **Zero Gravity Research Facility**
 - <http://microgravity.grc.nasa.gov/zero-g/index.html>
- **2.2 Second Drop Tower**
 - <http://microgravity.grc.nasa.gov/drop2/>
- **ZARM Drop Tower**
 - <http://www.zarm.uni-bremen.de/main.htm>
 - ZARM Drop Tower Bremen - Users Manual, Version 28, April 2000
- **JAMIC Drop Tower**
 - <http://www.jamic.co.jp/ENG/JAMIC/3.html>
- **Microgravity Carrier Summary**
 - http://microgravity.msfc.nasa.gov/NASA_Carrier_User_Guide.pdf
 - Ross, H. D. (2001) *Microgravity Combustion*, Academic Press



Microgravity Environment of Ground-based Facilities and Non-orbital Flight Platforms

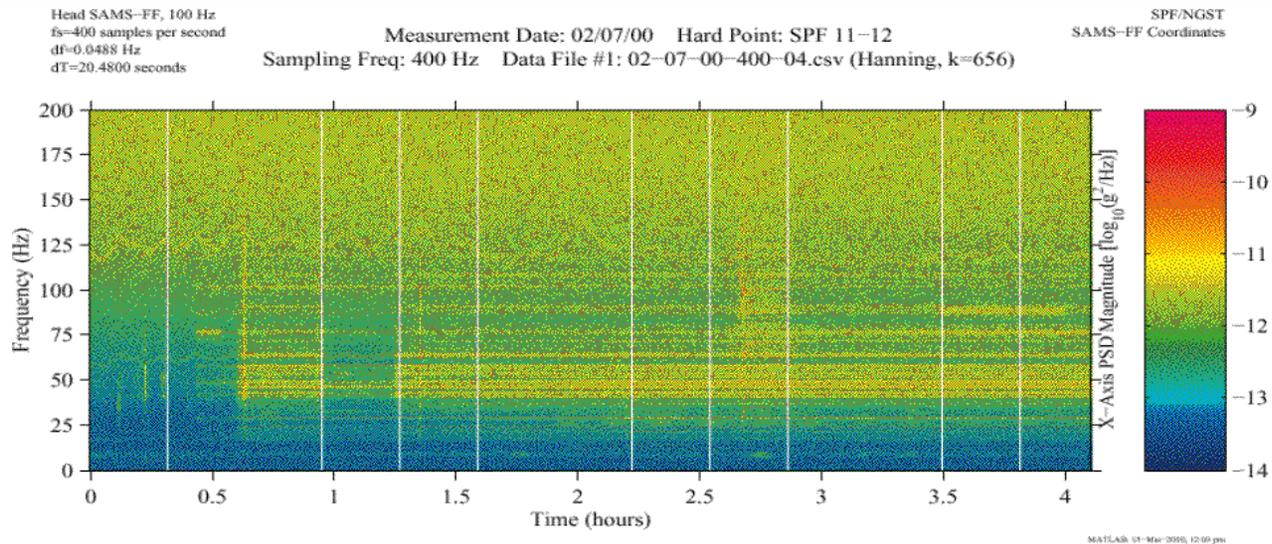
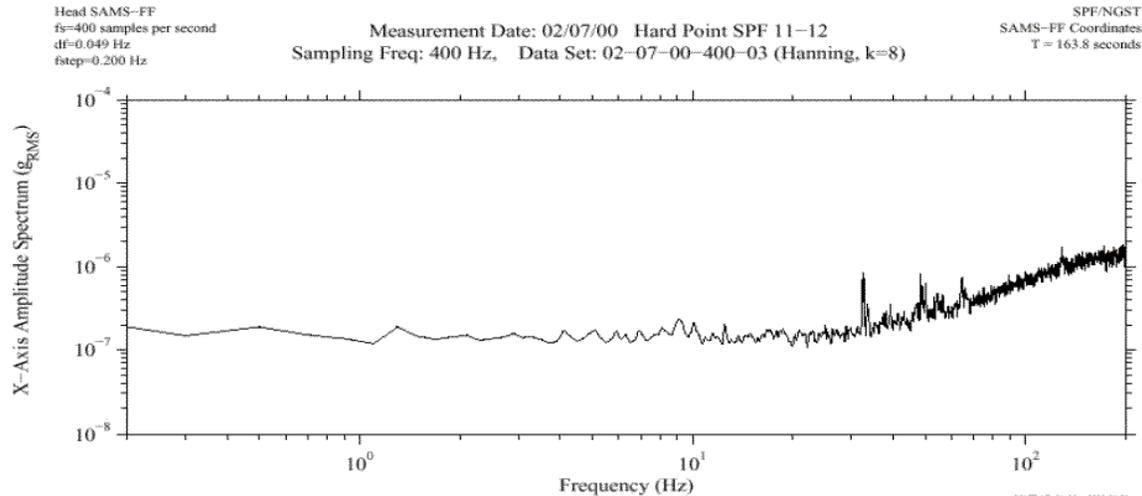


Figure 10-1: Ground Testing – SPF data

**Data from the vertical axis in NASA GRC
2.2 Second Drop Tower facility.**

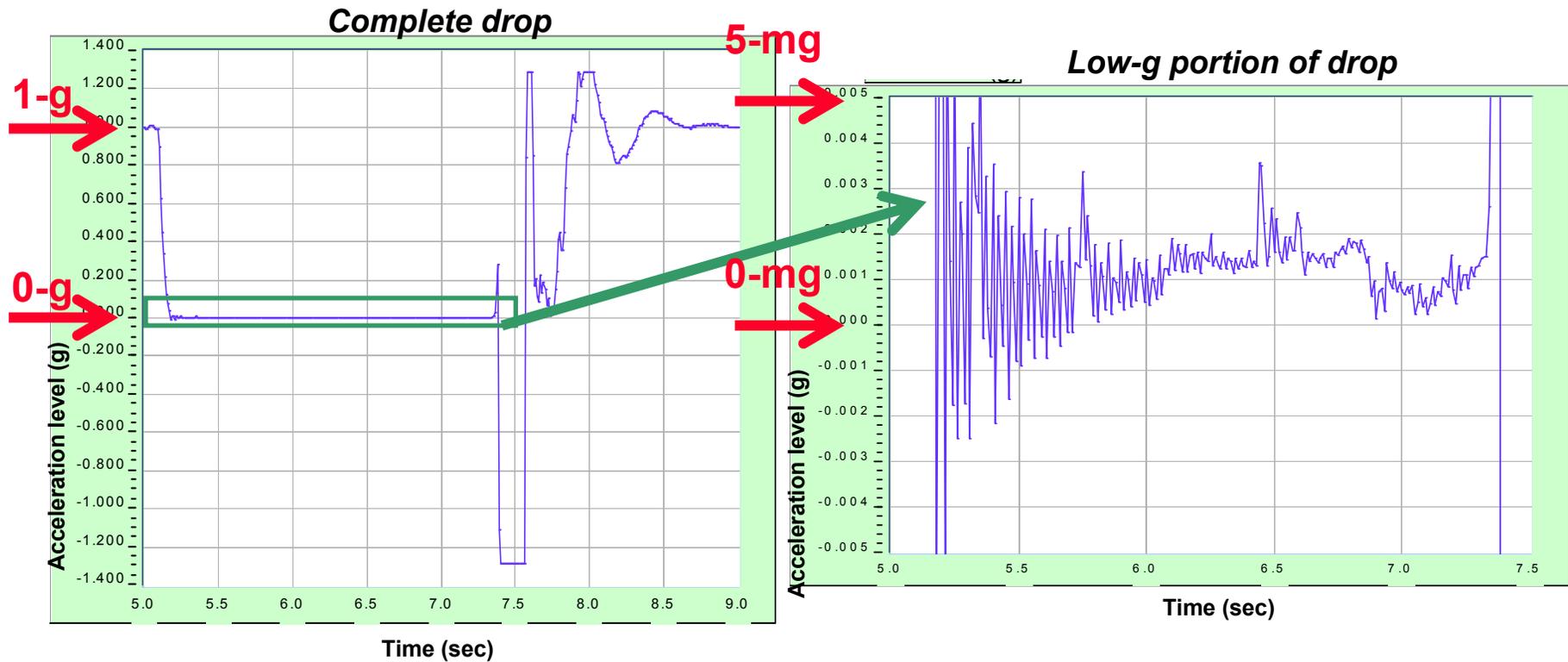
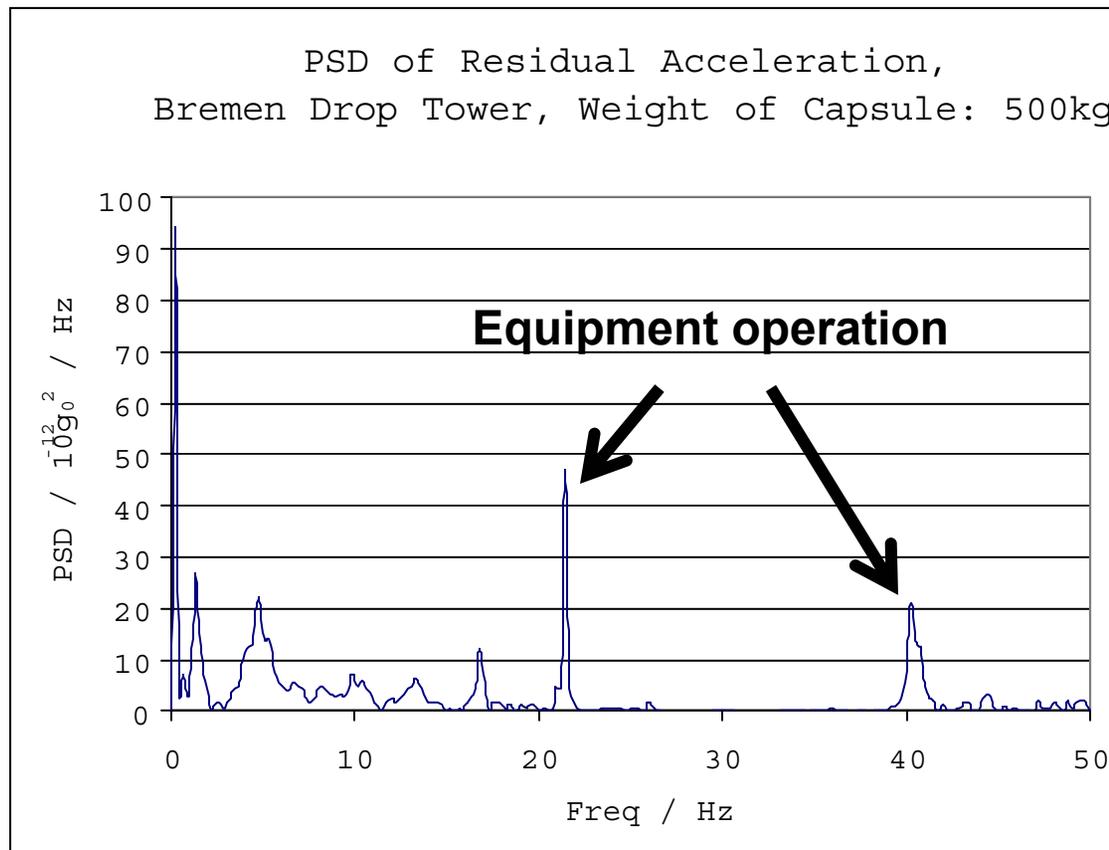


Figure 10-2: Acceleration level for drop tower test



**Figure 10-3: Power Spectral Density plot during drop (ZARM)
(note: release disturbances not included)**

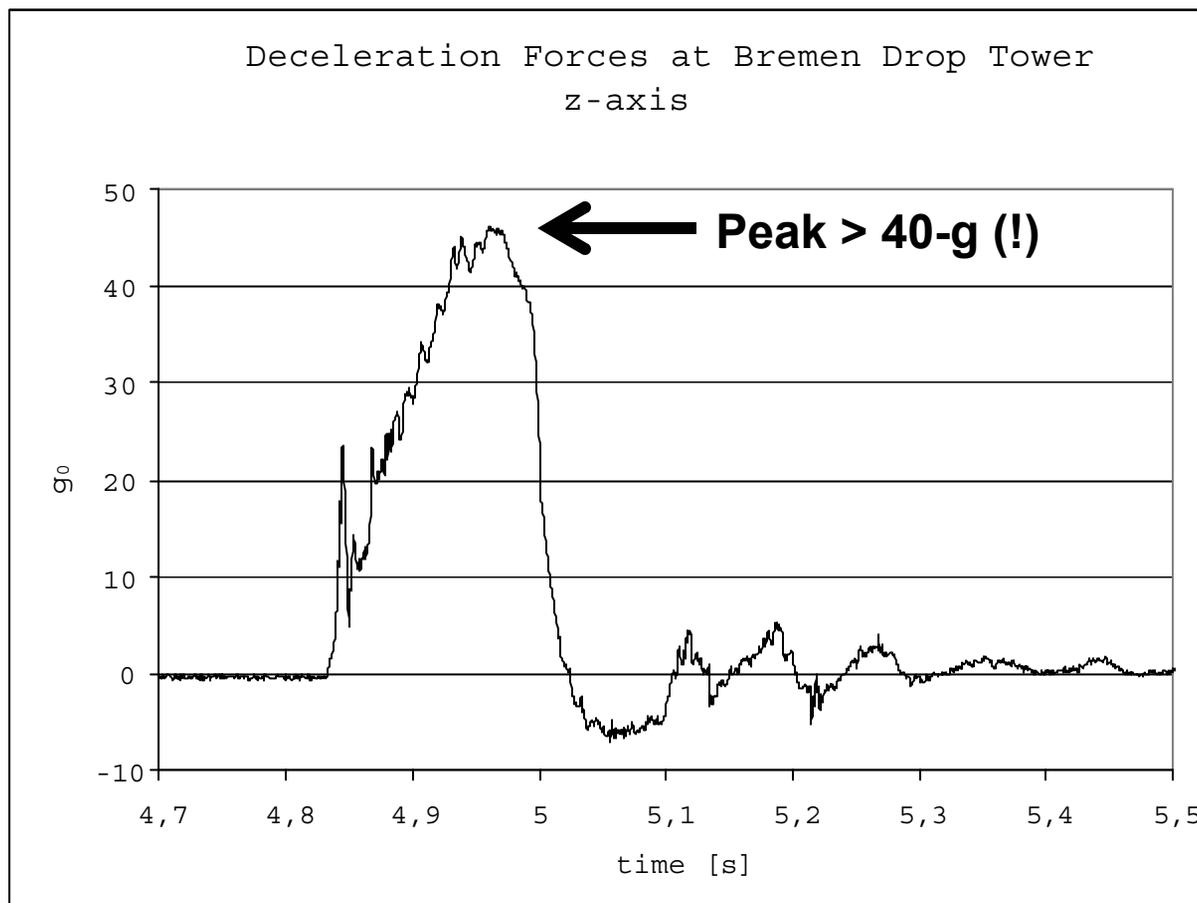


Figure 10-4: Deceleration at capture (ZARM)

Head C: 5.0 Hz
fs=25.0 samples per second

Multiple KC-135 Parabolas Without De-Meaning
MET Start at 055/15:09:59.992

KC-135
KC-135 Coordinates
T=300.0 seconds

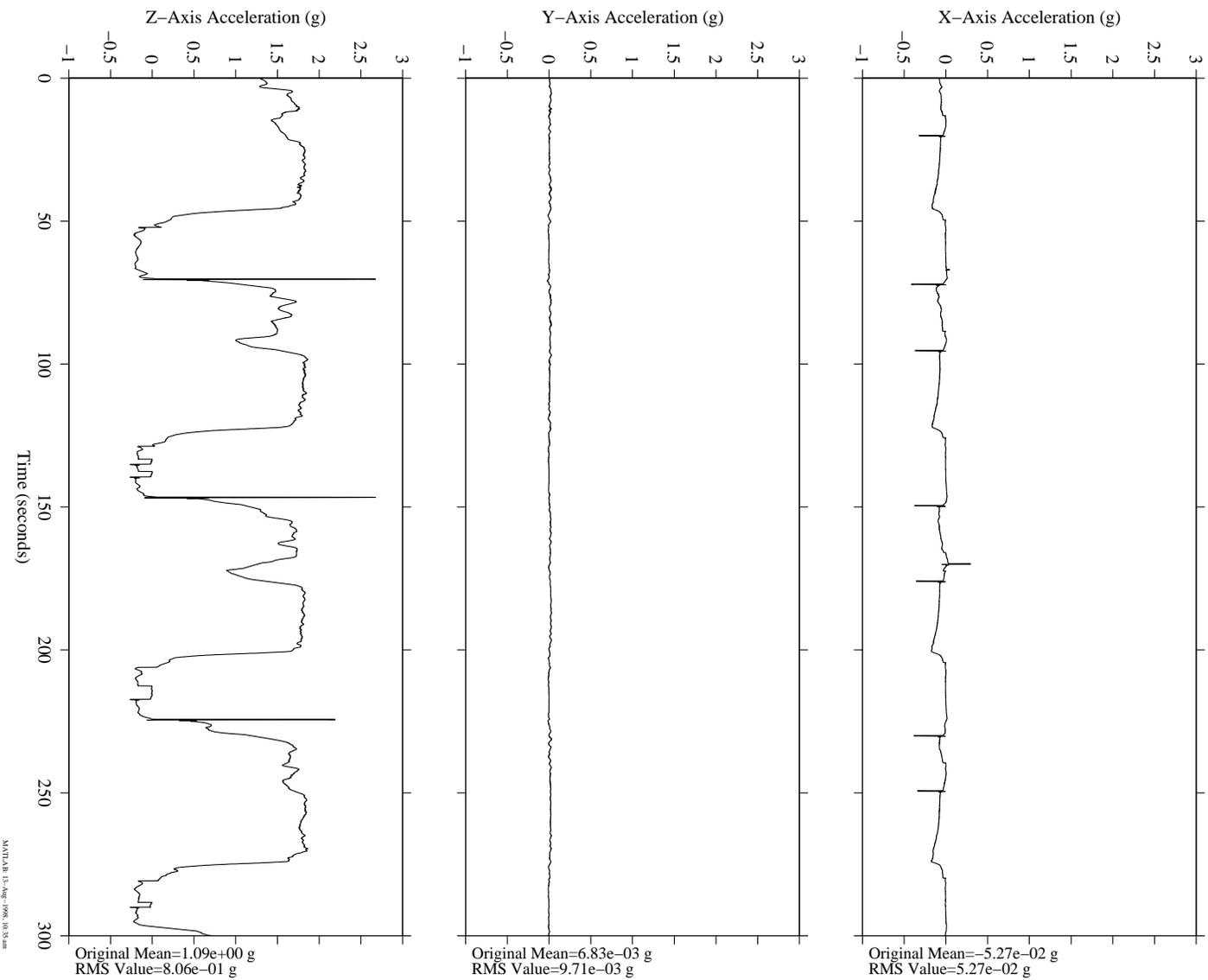


Figure 10-5

uSEG Mission: Reduced Gravity Portion of KC-135 Parabola Without De-Meaning

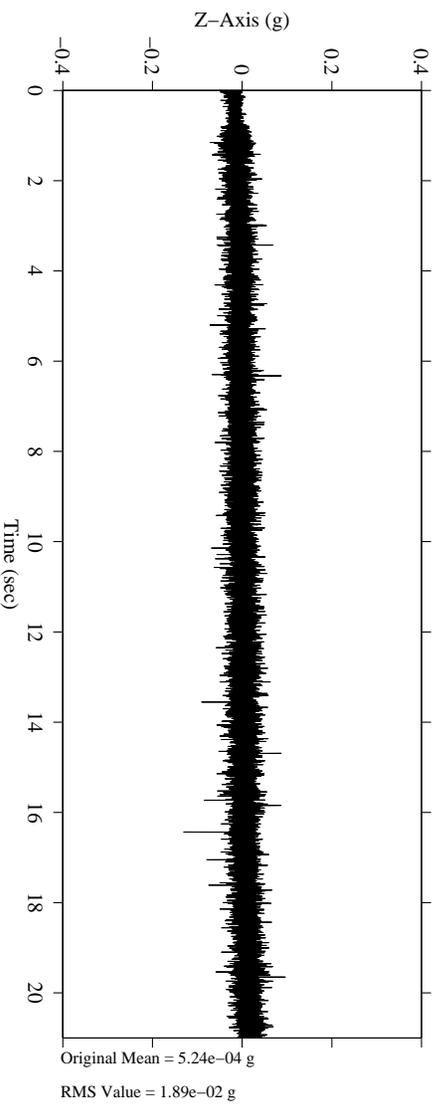
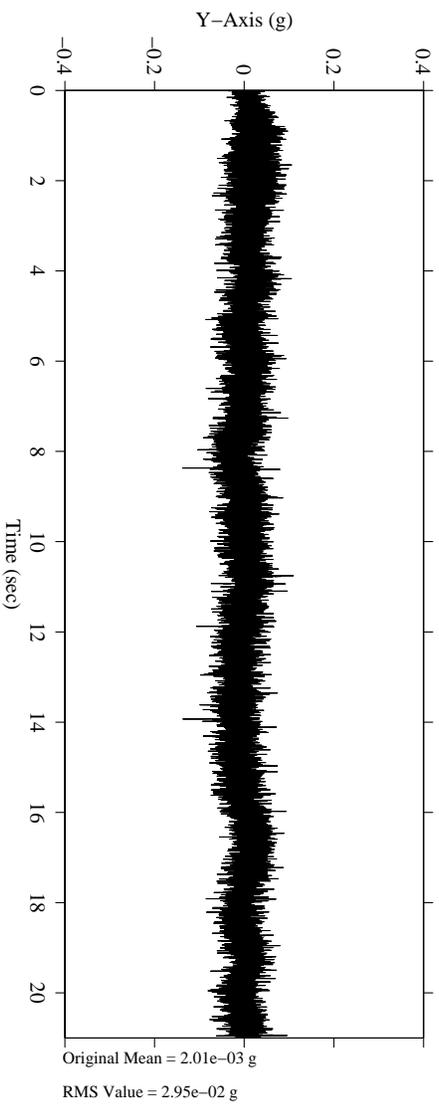
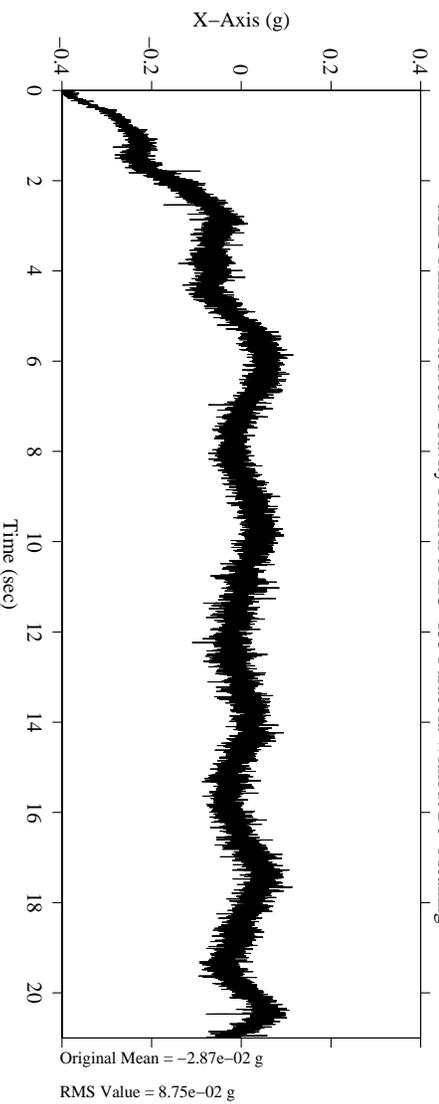
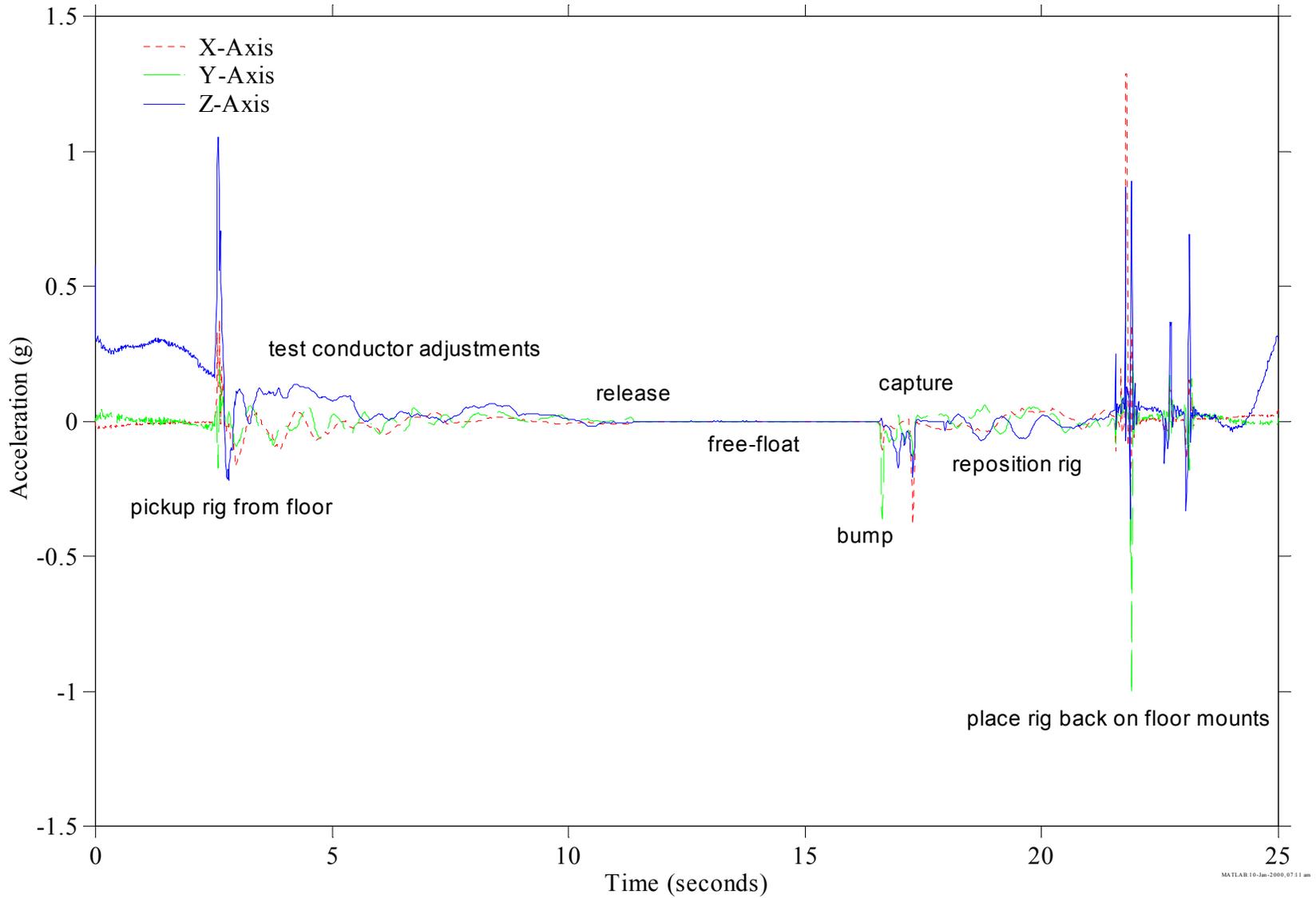


Figure 10-6

FREE-FLOAT
DATE: 04-27-99, FILE #0031

Figure 10-7



SAMS-FF Data Recorded in Support of SAL Experiment Showing Free-Float Interval

Head SAMS-FF, 50 Hz
fs=100 samples per second

Enhancement of Free Float Interval for Z-Axis
Data Set #31

KC-135 Free Float
April 27, 1999

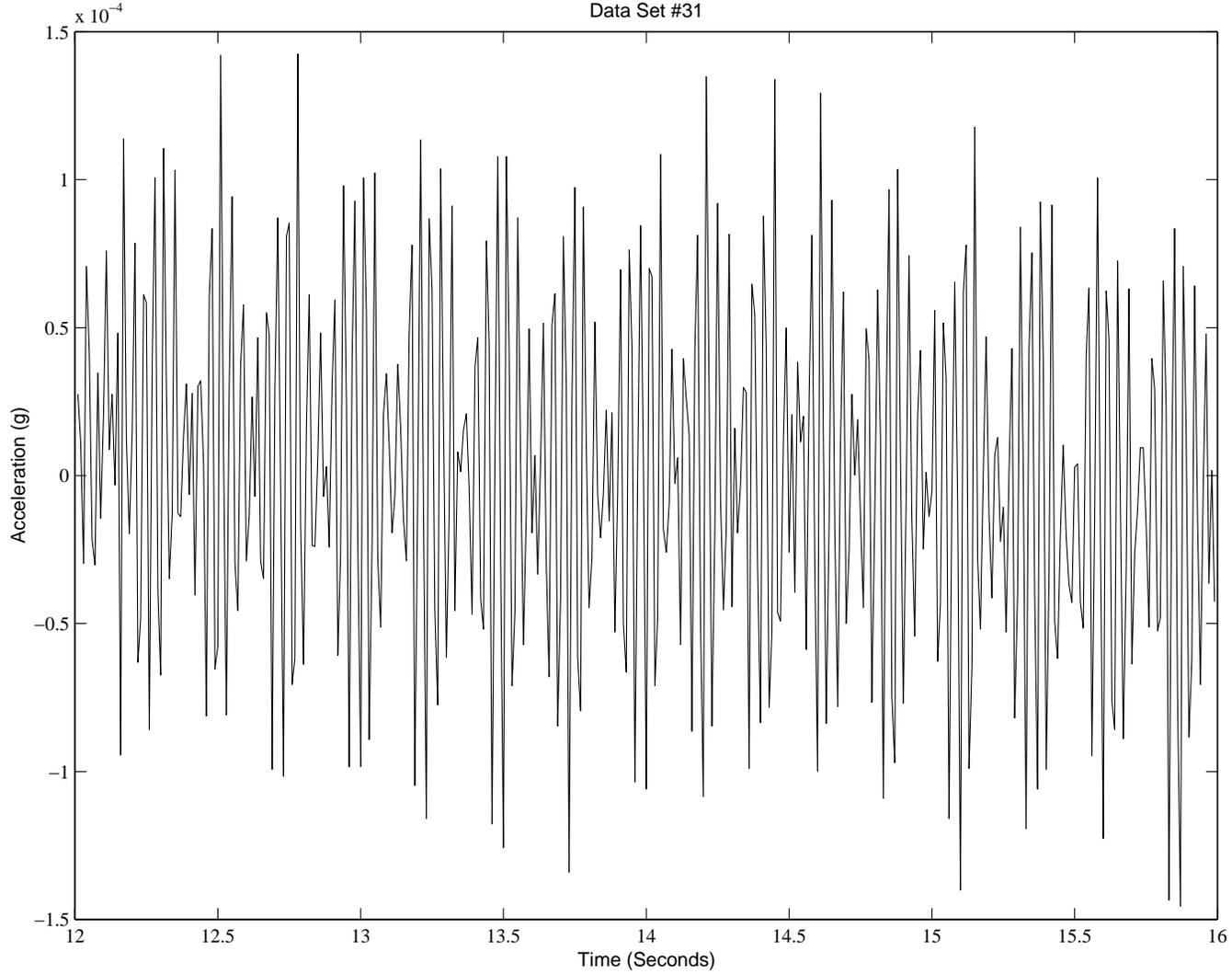


Figure 10-8

Figure 8-7: Enhancement of the Free Float Period for the Z-Axis

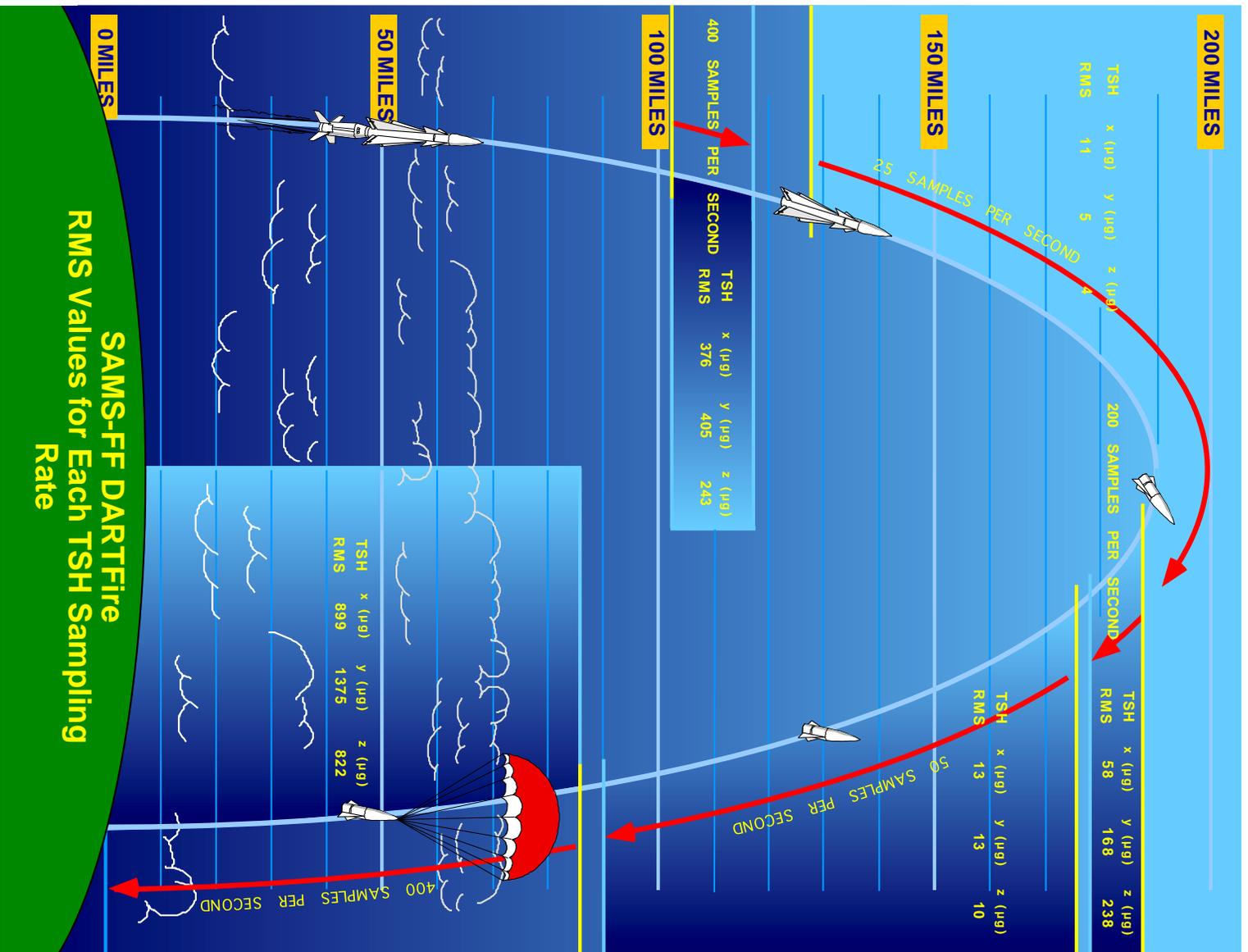
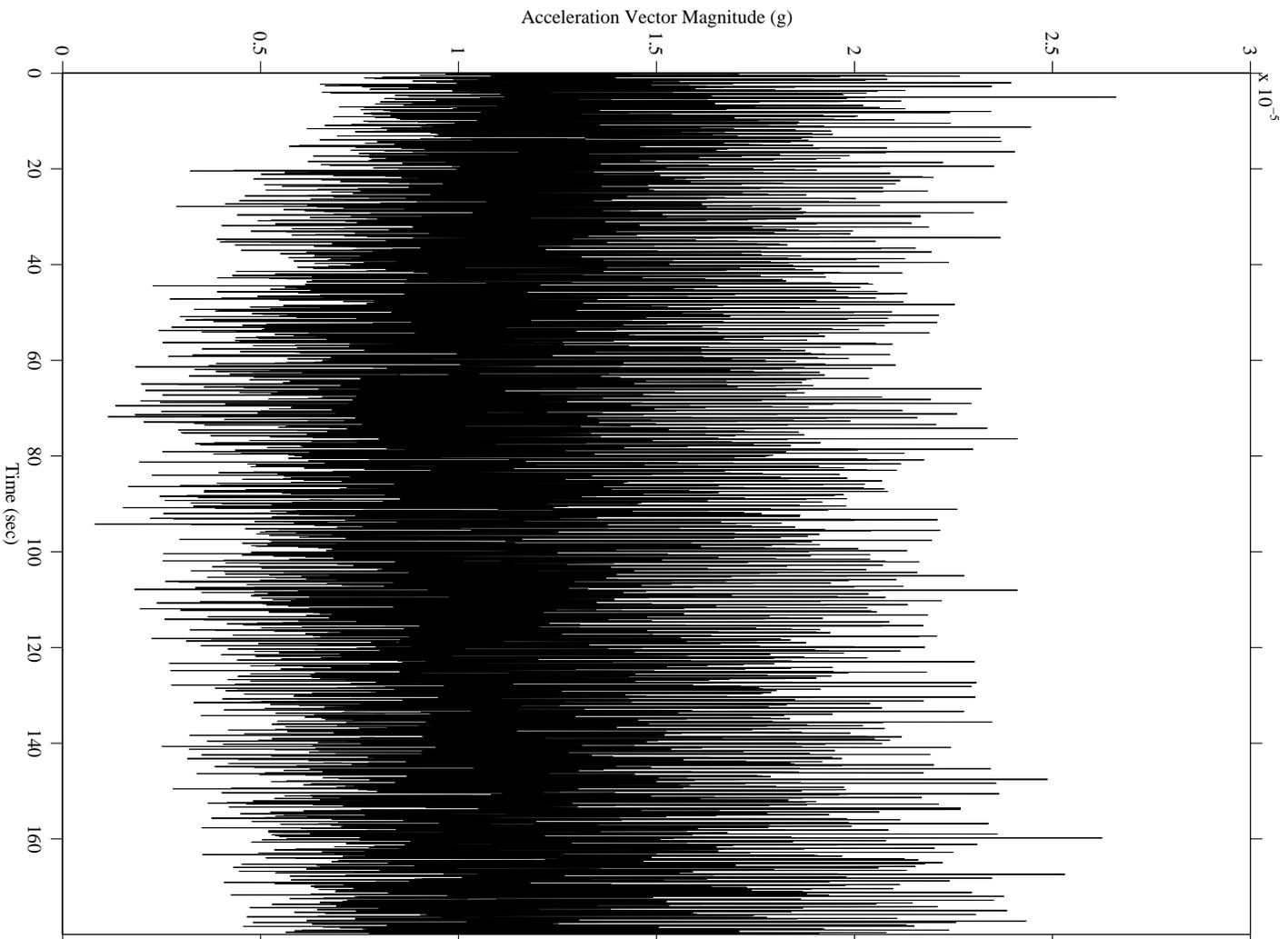


Figure 10-9

Head SAMS-FF DATA, 6.55 Hz
fs= 25 samples per second

MET Start at 000/00:02:05.027
Acceleration Vector Magnitude for Fs=25

DARTFire Mission
SAMS-FF Coordinates



MATLAB: 11-Aug-1998, 06:02 pm

Figure 10-10

Head SAMS-FP DATA, 6.55 Hz
fs = 25 samples per second
dF = 0.048828 Hz

MET Start at 000/00:02:05.027, Hanning k=8
RSS Power Spectral Density for Fs=25

DARTFire Mission
SAMS-FP Coordinates
T = 179.988 sec

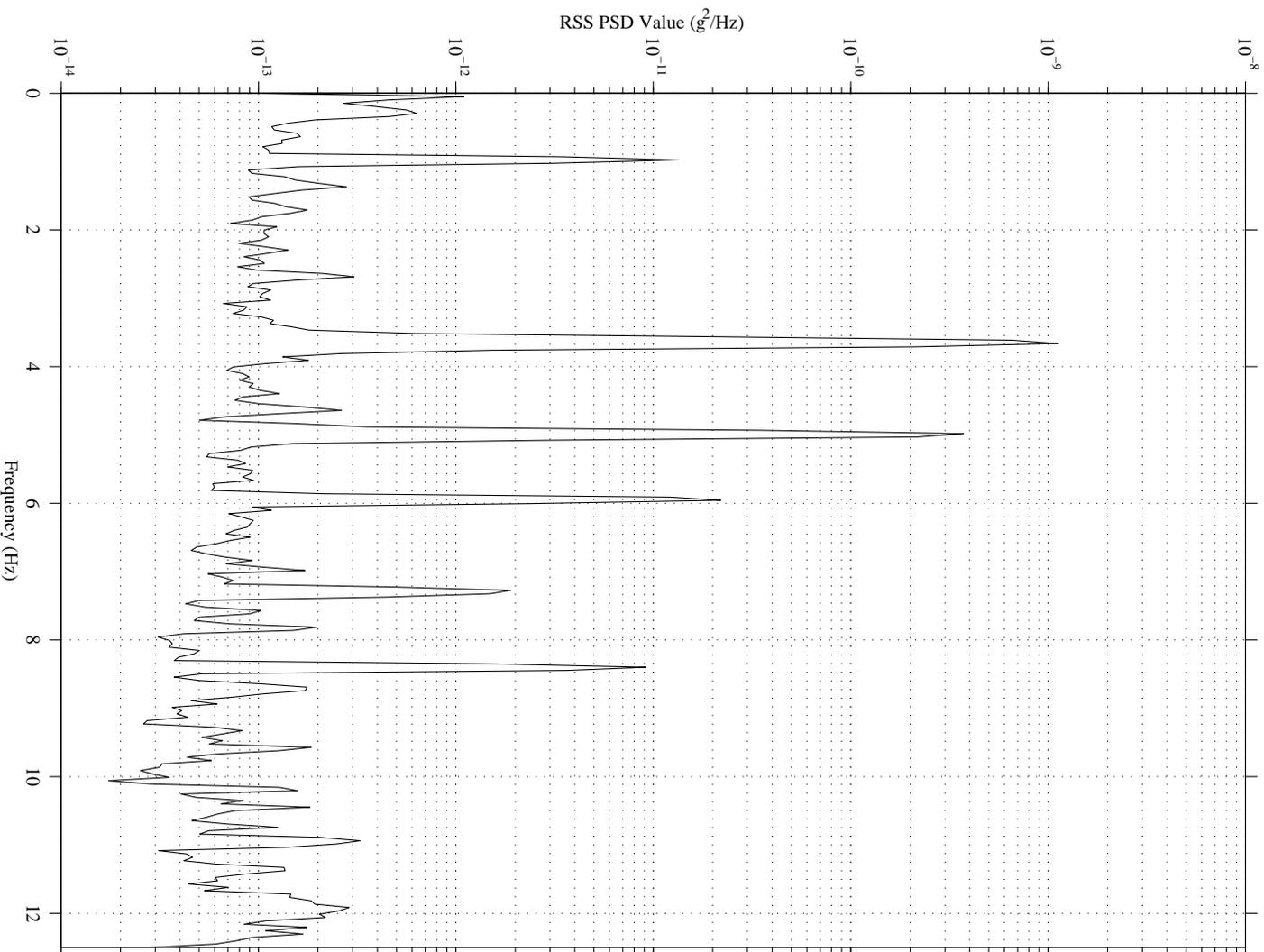


Figure 10-11